Quick Start Guide

Unbox, set up and power-on your robot in less than 30 minutes!

1. What’s inside
   - Robot
   - E-stop (package separate)
   - Gamepad (package separate)
   - Power supply
   - Ethernet cable
   - Mounting plate

2. Mounting and setup
   i. Open base shell clamp
   ii. Slide robot onto base
   iii. Close base shell clamp

3. Power-on
   i. Connect power supply to robot
   ii. Press Connect
   iii. Press E-stop

4. Connecting computer and configuring wired LAN settings
   i. Launch web browser (Chrome recommended)
   ii. Enter robot IP address in URL field
   iii. Enter admin admin
   iv. Click Connect

5. Exploring admittance control
   - Cartesinan admittance
     - Apply force by hand to move robot in admittance mode
   - Null space admittance
     - Null space while retaining end effector position

6. Controlling robot with gamepad
   - USB
   - Micro USB

7. Accessing the robot via KINOVÂ® KORTEX™ Web App
   i. Launch web browser (Chrome recommended)
   ii. Enter robot IP address in URL field
   iii. Enter admin admin
   iv. Click Connect

8. Playing a preset trajectory (sequence)
   i. Select preset sequence Demo Sequence
   ii. Play the sequence on blog

9. Going further: API, documentation and other resources
   - KINOVÂ® KORTEX™ GitHub repository
   - KINOVÂ® KORTEX™ ROS GitHub repository
   - ROS documentation
   - Technical support

There is no need too small, for task too great.