



Specifications

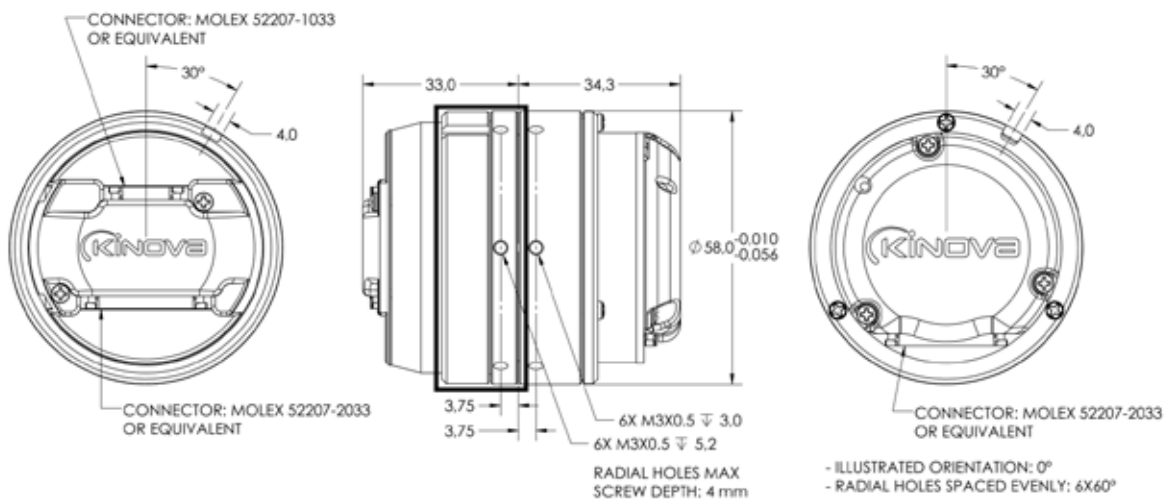


END EFFECTOR MOUNTING

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Version 1.1 - April 2017

The procedure to mount an end effector to MICO² (4/6 DOF) and JACO² (4/6/7 DOF) is the same. In all cases, the end effector is attached to a K-58 actuator. The mounting location (highlighted in black) and dimensions (mm) are provided in the following drawing.



The attachment of your end effector should be a circular part with 6 M3 screw holes. To facilitate the design of the end effector mounting part, download the CAD of the K-58 actuator at www.kinovarobotics.com/innovation-robotics/products/actuators.

⚠ The attachment for the gripper should be a circular part with 6 M3 screw holes. To facilitate the design of the end effector mounting part, download the CAD of the K-58 actuator here.

⚠ Note that there is a 4.0 mm groove on the actuator to correctly align the gripper and have a reference alignment for the robot's inverse kinematics.